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and outputs a different motion and force. The point of a mechanism is to make the job easier to do. A parallel-motion linkage creates an identical parallel

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is abandoned and the parameters describing the mechanism geometry are chosen in E.A. Dijkstra; Motion Geometry of (1976) E.A. Dijkstra;

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To confirm the range of motion, mechanisms were fixed in the extreme conformations Because the full geometry and motion path are known,

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A Strong Relationship Between New and Old Inversion Mechanisms. E. A. Dijkstra Harmonic Amplitudes of the Output Motion of Closed-Loop Linkage Mechanisms. IDETC

Mobile assemblies based on the bennett linkage |

Large mobile assemblies developed over the last three decades were based mostly on planar mechanisms, e.g. the Baker E.J; 2000 On the motion geometry of the

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Geometry constraint and branch motion evolution

This paper investigates the interesting bifurcated motion property of a class of 3-PUP parallel mechanisms which are classified by the angle between two prismatic

Dijkstra, e. a., motion geometry of mechanisms

Dijkstra, E. A., Motion Geometry of Mechanisms. Cambridge-London-New York-Melbourne. Cambridge University Press. 1976. XVI, 288 S., 9.25

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A novel classification of planar four-bar linkages

as a single degree of freedom in motion) (Dijksman 1976 Dijksman, E. A. 1976 Motion geometry of mechanisms. Cambridge University Press. Dijksman,

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Mechanisms: Parallel Motion Linkage: The parallel motion linkage can be used to make things move in the same direction a set distance apart.

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but is not necessary for the perception of volume since the motion parallax mechanism alone is mechanisms e.g. using of the geometry of

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